Introduction to mechanisms



This week: links, joint types, degrees of freedom, mobility, Grashof criterion

Next week: details of linkage analysis.

Disney animatronics linkages software in the news

article: <u>http://machinedesign.com/cad/new-role-kinematics-</u> software-defining-mechanized-dinosaurs

video: <u>http://www.youtube.com/watch?</u>
feature=player_embedded&v=DfznnKUwywQ

paper: <u>http://www.disneyresearch.com/wp-content/uploads/</u> <u>CDMC.pdf</u> What is actually going on?

PARAMETER SPACE EXPLORATION

A DATABASE OF REPRESENTATIVE CURVES IS GENERATED BY SAMPLING THE PARAMETER SPACE

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==> motivation to learn about Degrees of Freedom (DOF), joint types, mobility, Gruebler's formula







Gruebler's formula: $M = 3(N-1) - 2f_1 - f_2$

Four-Bar Mechanisms



Four-Bar Mechanisms



Grashof

shortest + longest < sum of the others



http://www.mekanizmalar.com/fourbar.html



Resources

Linkage Links page started on Canvas:

- interesting linkage examples
- linkage simulation software
- linkage analysis and design tools

This page is editable by the entire class. Please add discoveries!

For example: <u>http://mechanicaldesign101.com/2015/05/01/walking-machines/</u>

https://www.youtube.com/watch?v=SMnC25YPcHs

Final Project...

In previous years we have created:

turtles lemurs sloths hippogriffs elephant seals rabbits ducks horses dinosaurs dragons alligators (low+high walk) beetles...

What totally new thing will we do for 2016?

The answer is:



as in

pentapedal

New York Times July 2014 video

Force and power from each leg over the one stride:



For more details

- http://www.nytimes.com/2014/07/28/science/for-kangaroos-tailbecomes-a-fifth-leg.html
- S. O'Connor *et al.*, "The kangaroo's tail propels and powers pentapedal locomotion," <u>http://rsbl.royalsocietypublishing.org/content/10/7/20140381</u>