## Introduction to mechanisms



This week: links, joint types, degrees of freedom, mobility, Grashof criterion

Next week: details of linkage analysis.

## Disney animatronics linkages software in the news

article: http://machinedesign.com/cad/new-role-kinematics-software-defining-mechanized-dinosaurs
video: http://www.youtube.com/watch?
feature=player embedded\&v=DfznnKUwywQ
paper: http://www. disneyresearch.com/wp-content/uploads/ CDMC.pdf

## What is actually going on?

## PARAMETER SPACE EXPLORATION



A DATABASE OF REPRESENTATIVE CURVES IS GENERATED BY SAMPLING THE PARAMETER SPACE

## What is actually going on?


==> motivation to learn about Degrees of Freedom (DOF), joint types, mobility, Gruebler's formula


Mobility = ?


Gruebler's formula: $M=3(N-1)-2 f_{1}-f_{2}$

## Four-Bar Mechanisms



Four-Bar Mechanisms

## Grashof

## shortest + longest < sum of the others


http://www.mekanizmalar.com/fourbar.html


- Set speed to 0
- Change links, joints
- Reset speed


## Resources

Linkage Links page started on Canvas:

- interesting linkage examples
- linkage simulation software
- linkage analysis and design tools

This page is editable by the entire class. Please add discoveries!

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For example:
http://mechanicaldesign101.com/2015/05/01/walking-machines/
```

https://www.youtube.com/watch?v=SMnC25YPcHs

## Final Project...

In previous years we have created:
turtles
lemurs
sloths
hippogriffs
elephant seals rabbits
ducks
horses
dinosaurs
dragons
alligators (low+high walk)
beetles...

What totally new thing will we do for 2016 ?

The answer is:

## as in

## pentapedal

New York Times July 2014 video

Force and power from each leg over the one stride:

## serinshran mox



## For more details

http://www.nytimes.com/2014/07/28/science/for-kangaroos-tail-becomes-a-fifth-leg.html
S. O'Connor et al., "The kangaroo's tail propels and powers pentapedal locomotion," http://rsbl.royalsocietypublishing.org/content/10/7/20140381

